# Software for Engineer Design



# Lecture 01

## Introduction

Subjects:

- ✓ Theoretical Foundation
- ✓ The Matlab Interface
- ✓ Basic functionality of Matlab

# Keyword

Field, skill, package, simulation, image processing, differential equation.

### Abstract

Matlab is a widely used tool in all Engineering fields. There is no doubt that knowing at least the basics of Matlab is a valuable, if not essential skill to have. Matlab is a very versatile software package that can be expanded by any interest group to match their special computational needs. It is thus not only used for simple or complex arithmetic, but also in image processing, statistical analysis, simulation of many kinds, differential equations, etc.

We begin by looking at some of the very basic functionality of Matlab, like variable declarations, arithmetic, and vector and matrix data structures and manipulation. We then apply this foundation to more complex problems to solve those problems and learn about methods of displaying the solutions.

This lecture serves to build an understanding of the Matlab interface, basic mathematical operations, and the fundamental data structures.

#### **1.1 - Theoretical Foundation**

The Matlab Interface (Figure 1.1) is divided into 3 windows: The *Workspace* (upper left corner) lists all defined variables and mfiles (discussed later); the *Command History* (lower left corner) lists the ordered sequence of commands issued in this session; and the *Command Window* (right side) is the main source of input and output of commands, variable definitions, and errors.

In the toolbar of the interface, we can designate a directory from which to read and to which to write m-files. It is recommended to create a new directory (e.g. *matlab*) in your account (the *H*: drive in case of the Gateway Lab), which will host any m-files, exercises, and assignments. For simplicity, keep all Matlab related files in this directory.

Whenever starting Matlab, change the *Current Directory* to this directory to access relevant files.



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Figure 1.3 shows a few simple arithmetic expressions that are evaluated in the *Command Window*: Exponentials are typed in as x^y, square roots as sqrt(x). The *Workspace* and *Command History* Windows update as expressions are evaluated in the *Command Window*. Any variable that appears in the *Workspace* can be used. ans denotes the variable for the last evaluated answer.

Variable are formed by assigning letters or words to numbers or expressions, as shown in Figure 1.4. All defined variables in the *Workspace* can be used throughout the session.

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Using variables that haven't been defined returns an appropriate error.

Declarations must follow the convention of assignment where the left side of an equal sign is always a variable and the right side an arbitrary expression.



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Matlab handles variables by their value as opposed to symbolically. When a variable has been assigned to a value and is used in another expression, the variable acts as the value rather than a reference to the variable name. We can observe this behavior in the series of expressions in Figure 1.6. Even though **a**+**b** has been declared in terms of variables **a** and **b**, when changing the value of **a**, **c** remains to be the sum of the initial **a** and **b**.





The contents of the *Workspace* can be cleared by issuing the command **clear** . This will remove all previously defined variables.



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The contents of all windows can be cleared from the *Edit* menu.

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[**x:z**] defines a vector of numbers starting at **x** and ending at **z**, where each element of the array is incremented by **1**. E.g. [**3:9**] defines the vector [*3*,*4*,*5*,*6*,*7*,*8*,*9*].

[x:y:z] defines a vector of numbers starting at x and ending at z, where each element of the array is incremented by y. E.g.
[10:2:20] defines the vector [10,12,14,16,18,20].

Every definition explicitely returns the defined quantity, and each expression returns a result. The output can be suppressed by ending the expression with a ; (semicolon). E.g.

a=[1:1000000] returns a vector of 1000000 elements, a quantity that we do not necessarily want to see see element by element. The expression

a=[1:1000000]; will merely define the variable without returning unwanted output.

Figure 1.10 pictorially shows the difference between scalars and vectors: a scalar is a single element, while a vector is a series (or a list) of elements (of scalars).

In Figure 1.9 we have declared a scalar **s** and a vector **t**.



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 Scalar

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 Vector (Array)

Having defined a vector and a scalar, we can perform arithmetic operations. Adding (multiplying, etc.) a vector by a scalar adds (multiplies, etc.) each element of the vector by the scalar. The result of  $\mathbf{s} \times \mathbf{t}$ can be assigned to an output variable  $\mathbf{u}$  as in  $\mathbf{u} = \mathbf{s} \times \mathbf{t}$ . Variable  $\mathbf{u}$  then references the resulting vector.



Click image to enlarge, or click <u>here</u> to open

Two same-sized vectors  $\mathbf{a}$ and  $\mathbf{b}$  are added/subtracted element-by-element using the + and - operators, as is done in matrix addition and subtraction. (Vectors are merely matrices with only one row).

In order to multiply two vectors element-byelement, the operator \* (or /) must be preceded by a period ., as shown in Figure 1.12.



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In order to perform any element-by-element operation on two vectors, their lengths must match, otherwise Matlab returns an error.

Figure 1.14 shows how two differently sized vectors cannot be combined element-by-element, because there exist ambiguities as to how an operation is defined between a scalar and a "nothing".

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#### Figure 1.13

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Figure 1.16 pictorially shows a transpose and a double transpose operation.

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Figure 1.16

Elements in a vector can be addressed individually by enclosing the elements index in parentheses after the vector variable name, e.g. **b(3)** . The vector's elements' indices start at 1 and stop at the length of the vector. Index 0 (zero) is not used, even though it is commonly done so in programming languages.

The command **length (b)** for any matrix **b** evaluates to the number of elements in vector **b**.

A matrix is defined by rows and columns. A row of elements is delimited by commas, e.g. 1,2,3. Columns are delimited by semi-colons, e.g. 5;6;7. A matrix can thus be defined using any of the vector defining notations used previously, e.g. [1,2,3;4,5,6;7,8,9]or

Figure 1.19 pictorially shows what are considered rows and columns of a matrix, indexing conventions, and the general form of indexing into a matrix.







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Matrices of same dimensions can be added and subtracted as is defined in matrix arithmetic. In multiplication, however, we achieve different results depending on whether we multiply two matrices by using abo or a by, where the latter is element-byelement multiplication.

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Random numbers, vectors, and matrices can be formed using the function **rand**. rand takes as arguments the number of rows, and number of columns: rand(rows.cols) and returns a matrix of that size with random numbers ranging from 0 to 1. The function can easily be multiplied and/or added to scalars in order to produce random numbers in any range, e.g. a random number between 0 and 10: **rand(1,1)** , or a random number between 10 and 100:

Matrices and vectors can be appended to form larger matrices and vectors. Given two similarly or differently sized vectors **a** and **b**, a vector **c** can be formed by [a,b] . c is now as long as **a** and **b** combined. The same holds for matrices. A 3x3 matrix **a** can be combined with a 3x5 matrix **b** by **[a,b]** but not by [a;b], while a 3x3 matrix **a** can be combined with a 5x3 matrix **b** by [a;b] but not by [a,b] . Depending on which way matrices are appended, one of the dimensions (rows or columns) must match.





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Functions **ceil(x)** and **floor(x)** round decimal numbers (doubles) up and down to the next integer, respectively. This operation can be performed on scalars, vectors, and matrices.

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Elements in a matrix can be accessed by rows and columns: **A**(**r**,**c**), where **A** is a matrix, **r** is a row, and **c** is a column.



Rows and columns can also be accessed. To access a row in matrix **A**, a colon (:) is substituted for the column, and vice versa:



The concept of indexing into a matrix by row and column, only row, and only column is pictorially described in Figure 1.26.

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It is also possible to extract portions of a matrix by using ranges such as **[1,2]** or **[1:3]** as indices, as shown in Figure 1.27.

The concept of extracting sub-matrices from matrices is shown in Figure 1.28.

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Figure 1	.28								

Not only can we extract a sub-matrix, but we can also replace portions of a matrix. The same form of indexing is used, as shown in Figure 1.29.

The concept of replacing sub-matrices is pictorially described in Figure 1.30.

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To get quick help on any Matlab function, we type **help function** where **function** is the name of the function. **help rand**, for example, gives detailed help on function **rand**.



Click image to enlarge, or click here to open

To save a collection of expressions, for example for in-class exercises and homework assignments, you will need to use mfiles. M-files are no more than simple text files that can be executed from within Matlab to reproduce the statements in the m-file.

To create a new m-file, go to *File* -> *New* -> *M-file*, as shown in Figure 1.32.



Click image to enlarge, or click here to open

We can now enter a number of statements, one statement per line. In a later lecture, we will see how to create functions using m-files.



Click image to enlarge, or click <u>here</u> to open

Save the m-file in the *matlab* directory which you have earlier chosen as the *Current Directory*. Make sure that the extension of this file is **.m**, i.e. make sure that the file ends with **.m** 

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You can now execute the statements in the m-file by typing in the name of the m-file in the *Command Window*. Make sure to omit the **.m** extension.

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