Artificial Intelligence

Mongolian University of Science and Technology
Power Engineering School

T.Uranchimeg Prof. Dr.

Source
http://www.aaai.org/AITopics/pmwiki/pmwiki.php/AITopics/BriefHistory
Subjects

- Modern history
- 1956 - 1962
- 1963 - 1990
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Modern history
1956 - John McCarthy coined the term "artificial intelligence" as the topic of the **Dartmouth Conference**, the first conference devoted to the subject.

Demonstration of the first running AI program, the Logic Theorist (LT) written by Allen Newell, J.C. Shaw and Herbert Simon (Carnegie Institute of Technology, now Carnegie Mellon University).
1957, 1952-62

- The General Problem Solver (GPS) demonstrated by Newell, Shaw & Simon.

- Arthur Samuel (IBM) wrote the first game-playing program, for checkers, to achieve sufficient skill to challenge a world champion. Samuel's machine learning programs were responsible for the high performance of the checkers player.
1958

- John McCarthy (MIT) invented the Lisp language.

- Herb Gelernter & Nathan Rochester (IBM) described a theorem prover in geometry that exploits a semantic model of the domain in the form of diagrams of "typical" cases.

- Teddington Conference on the Mechanization of Thought Processes was held in the UK and among the papers presented were John McCarthy's *Programs with Common Sense*, Oliver Selfridge's "Pandemonium," and Marvin Minsky's "Some Methods of Heuristic Programming and Artificial Intelligence."
Late 50's & Early 60's

- Margaret Masterman & colleagues at Cambridge design **semantic nets** for **machine translation**. See Themes in the work of Margaret Masterman by Yorick Wilks (1988).

- 1961 - James Slagle (PhD dissertation, MIT) wrote (in Lisp) the first symbolic integration program, SAINT, which solved calculus problems at the college freshman level.
First industrial robot company, Unimation, founded.

Thomas Evans' program, ANALOGY, written as part of his PhD work at MIT, demonstrated that computers can solve the same analogy problems as are given on IQ tests.

Ivan Sutherland's MIT dissertation on Sketchpad introduced the idea of interactive graphics into computing.

Links

- http://www.aaai.org/AlTopics/pmwiki/pmwiki.php/AlTopics/BriefHistory
- http://www.haskins.yale.edu/featured/heads/simulacra.html
- http://www.gutenberg.org/etext/15114
- http://www.computerhistory.org/babbage/
1964

- Danny Bobrow's dissertation at MIT (tech.report #1 from MIT's AI group, Project MAC), shows that computers can understand natural language well enough to solve algebra word problems correctly.

- Bert Raphael's MIT dissertation on the SIR program demonstrates the power of a logical representation of knowledge for question-answering systems.
1965

- J. Alan Robinson invented a mechanical proof procedure, the Resolution Method, which allowed programs to work efficiently with formal logic as a representation language. (See Carl Hewitt's *history of logic programming*).

- Joseph Weizenbaum (MIT) built ELIZA, an interactive program that carries on a dialogue in English on any topic. It was a popular toy at AI centers on the ARPA-net when a version that "simulated" the dialogue of a psychotherapist was programmed.
1966

- Ross Quillian (PhD dissertation, Carnegie Inst. of Technology; now CMU) demonstrated semantic nets.

- First Machine Intelligence workshop at Edinburgh - the first of an influential annual series organized by Donald Michie and others.

- Negative report on machine translation kills much work in Natural Language Processing (NLP) for many years.
1967

- Dendral program (Edward Feigenbaum, Joshua Lederberg, Bruce Buchanan, Georgia Sutherland at Stanford) demonstrated to interpret mass spectra on organic chemical compounds. First successful knowledge-based program for scientific reasoning.

- Joel Moses (PhD work at MIT) demonstrated the power of symbolic reasoning for integration problems in the Macsyma (PDF file) program. First successful knowledge-based program in mathematics.

- Richard Greenblatt at MIT built a knowledge-based chess-playing program, MacHack, that was good enough to achieve a class-C rating in tournament play.
Late 60s

- Doug Engelbart invented the mouse at SRI.
1969

- SRI robot, Shakey, demonstrated combining locomotion, perception and problem solving.

- Roger Schank (Stanford) defined conceptual dependency model for natural language understanding. Later developed (in PhD dissertations at Yale) for use in story understanding by Robert Wilensky and Wendy Lehnert, and for use in understanding memory by Janet Kolodner.

- First International Joint Conference on Artificial Intelligence (IJCAI) held in Washington, D.C.
Jaime Carbonell (Sr.) developed SCHOLAR, an interactive program for computer-aided instruction based on semantic nets as the representation of knowledge.

Bill Woods described Augmented Transition Networks (ATN's) as a representation for natural language understanding.

Patrick Winston's PhD program, ARCH, at MIT learned concepts from examples in the world of children's blocks.
Early 70's

- Jane Robinson & Don Walker established influential Natural Language Processing group at SRI.
- 1971 - Terry Winograd's PhD thesis (MIT) demonstrated the ability of computers to understand English sentences in a restricted world of children's blocks, in a coupling of his language understanding program, SHRDLU, with a robot arm that carried out instructions typed in English.
1972-74

- Prolog developed by Alain Colmerauer.
- The Assembly Robotics group at Edinburgh University builds Freddy, the Famous Scottish Robot, capable of using vision to locate and assemble models.
- Ted Shortliffe's PhD dissertation on MYCIN (Stanford) demonstrated the power of rule-based systems for knowledge representation and inference in the domain of medical diagnosis and therapy. Sometimes called the first expert system.
- Earl Sacerdoti developed one of the first planning programs, ABSTRIPS, and developed techniques of hierarchical planning.
Marvin Minsky published his widely-read and influential article on Frames as a representation of knowledge, in which many ideas about schemas and semantic links are brought together.

The Meta-Dendral learning program produced new results in chemistry (some rules of mass spectrometry) the first scientific discoveries by a computer to be published in a refereed journal.
Mid 70's

- Barbara Grosz (SRI) established limits to traditional AI approaches to discourse modeling. Subsequent work by Grosz, Bonnie Webber and Candace Sidner developed the notion of "centering", used in establishing focus of discourse and anaphoric references in NLP.

- Alan Kay and Adele Goldberg (Xerox PARC) developed the Smalltalk language, establishing the power of object-oriented programming and of icon-oriented interfaces.

- David Marr and MIT colleagues describe the "primal sketch" and its role in visual perception.
Doug Lenat's AM program (Stanford PhD dissertation) demonstrated the discovery model (loosely-guided search for interesting conjectures).

Randall Davis demonstrated the power of meta-level reasoning in his PhD dissertation at Stanford.
Late 70's

Stanford's SUMEX-AIM resource, headed by Ed Feigenbaum and Joshua Lederberg, demonstrates the power of the ARPAnet for scientific collaboration.
1978

- Tom Mitchell, at Stanford, invented the concept of Version Spaces for describing the search space of a concept formation program.

- Herb Simon wins the Nobel Prize in Economics for his theory of bounded rationality, one of the cornerstones of AI known as "satisficing".

- The MOLGEN program, written at Stanford by Mark Stefik and Peter Friedland, demonstrated that an object-oriented representation of knowledge can be used to plan gene-cloning experiments.
Bill VanMelle's PhD dissertation at Stanford demonstrated the generality of MYCIN's representation of knowledge and style of reasoning in his EMYCIN program, the model for many commercial expert system "shells".

Jack Myers and Harry Pople at University of Pittsburgh developed INTERNIST, a knowledge-based medical diagnosis program based on Dr. Myers' clinical knowledge.

Cordell Green, David Barstow, Elaine Kant and others at Stanford demonstrated the CHI system for automatic programming.

The Stanford Cart, built by Hans Moravec, becomes the first computer-controlled, autonomous vehicle when it successfully traverses a chair-filled room and circumnavigates the Stanford AI Lab.

Drew McDermott & Jon Doyle at MIT, and John McCarthy at Stanford begin publishing work on non-monotonic logics and formal aspects of truth maintenance.
1980's

- Lisp Machines developed and marketed.
- First expert system shells and commercial applications.
- 1980 - Lee Erman, Rick Hayes-Roth, Victor Lesser and Raj Reddy published the first description of the blackboard model, as the framework for the HEARSAY-II speech understanding system.
- First National Conference of the American Association of Artificial Intelligence (AAAI) held at Stanford.
1981

- Danny Hillis designs the connection machine, a massively parallel architecture that brings new power to AI, and to computation in general. (Later founds Thinking Machines, Inc.)

- 1983 - John Laird & Paul Rosenbloom, working with Allen Newell, complete CMU dissertations on SOAR.

- James Allen invents the Interval Calculus, the first widely used formalization of temporal events.
Mid 80's

- Neural Networks become widely used with the Backpropagation algorithm (first described by Werbos in 1974).

- 1985 - The autonomous drawing program, Aaron, created by Harold Cohen, is demonstrated at the AAAI National Conference (based on more than a decade of work, and with subsequent work showing major developments).

1989

- Dean Pomerleau at CMU creates ALVINN (An Autonomous Land Vehicle in a Neural Network), which grew into the system that drove a car coast-to-coast under computer control for all but about 50 of the 2850 miles.

- 1990's Major advances in all areas of AI, with significant demonstrations in machine learning, intelligent tutoring, case-based reasoning, multi-agent planning, scheduling, uncertain reasoning, data mining, natural language understanding and translation, vision, virtual reality, games, and other topics. Rod Brooks' COG Project at MIT, with numerous collaborators, makes significant progress in building a humanoid robot.
Early 90's

- TD-Gammon, a backgammon program written by Gerry Tesauro, demonstrates that reinforcement learning is powerful enough to create a championship-level game-playing program by competing favorably with world-class players.

- 1997 The Deep Blue chess program beats the current world chess champion, Garry Kasparov, in a widely followed match. First official Robo-Cup soccer match featuring table-top matches with 40 teams of interacting robots and over 5000 spectators.
Late 90's

- Web crawlers and other AI-based information extraction programs become essential in widespread use of the world-wide-web.

- Demonstration of an Intelligent Room and Emotional Agents at MIT's AI Lab. Initiation of work on the Oxygen Architecture, which connects mobile and stationary computers in an adaptive network.
Interactive robot pets (a.k.a. "smart toys") become commercially available, realizing the vision of the 18th cen. novelty toy makers.

Cynthia Breazeal at MIT publishes her dissertation on Sociable Machines, describing KISMET, a robot with a face that expresses emotions.

The Nomad robot explores remote regions of Antarctica looking for meteorite samples.
From Fantasy and Fact
Artificial intelligence has come far since its inception, both in its practical applications and in the popular imagination.
1950: The mathematician, Alan Turing proposes a test for machine intelligence.
1956: John McCarthy coins the term “artificial intelligence” as the topic of the Dartmouth Conference, the first conference devoted to the subject.
1959: Arthur Samuel’s checkers program wins games against the best human players.
1962: First industrial robot company, Unimation, founded.
1971: Terry Winograd’s Ph.D. thesis, (M.L.) demonstrated the ability of computers to understand English sentences in a restricted world of children’s blocks, in a coupling of his language-understanding program with a robot arm that carried out instructions typed in English.
1977: CSGO and ST22 star in “Star Wars.”
1997: IBM’s Deep Blue chess program beats the world chess champion Garry Kasparov in a widely followed match.
2006: Stanley, a robot Volkswagen Touareg, designed by a team of Stanford University engineers, wins the DARPA Grand Challenge award by traveling autonomously for 132 miles through a desert.
Reading materials

- http://library.thinkquest.org/2705/history.html
- http://www.stottlerhenke.com/ai_general/history.htm
- http://www.idsia.ch/~juergen/ai.html***
End of

Any questions?
Conclusion

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